

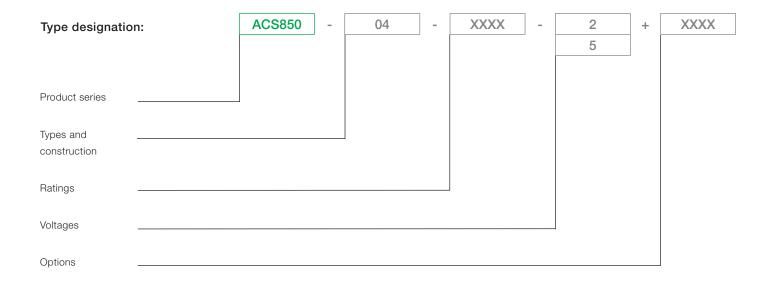
Low voltage AC drives

ABB machinery drives ACS850 0.5 to 700 hp / 0.37 to 560 kW Catalog

Selecting and ordering your drive

Type designation is a unique reference number that clearly identifies the drive by construction, power and voltage rating and selected options. Using the type designation you can specify your drives from the wide range of options available. Options are added to the type designation using the corresponding "plus" (+) code.

Build up your own ordering code using the type designation key below or contact your local ABB drives sales office and let them know what you want. Use page 3 as a reference section for more information.



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ABB machinery drives

ACS850	-	04	04 - XXXX		-	2	+	XXXX
						5		

ABB machinery drives are designed to meet the production and performance needs of machine builders, system integrators, panel builders and end users in a broad range of applications. ACS850 drives are ideal for applications like cranes, extruders, winches, conveyors, winders, pumps, fans and mixers in industries such as material handling, plastic and rubber, food and beverage, textile and metals.

The drives can be configured to meet the precise needs of these industries, as order-based configuration is an integral part of the offering. Covering a wide power and voltage range with standard and optional features, the drives are readily programmable, making their adaptation to different applications easy.

Wide range of options

ACS850 drives offer a wide range of built-in options such as different I/O and communications. A wide selection of external accessories is also available. The flexibility and programmability of the drives make them suitable for many applications in different areas of industry.

Robust design

The current ratings of ABB machinery drives are designed for applications that have a high overload requirement. At the heart of the drive is the motor control platform, direct torque control (DTC) that provides accurate motor torque and speed control even without feedback. The drive is designed for a long working life and as such, parts like fans and capacitors are selected to maximize their lifetime. This, together with the extensive protection features and design details such as coated boards, results in excellent reliability for the demanding industrial market.

Optimized cabinet assembly

ACS850 drives are designed to be built into a customer's own cabinet, using minimal cabinet space while ensuring that cabinet assembly is as easy as possible. The drives can be mounted side-by-side and cabinet assembly documentation is included. The documentation gives examples of different cabinet configurations, examples of drawings and hints on the selection of auxiliary equipment.



Main features

Feature	Advantage	Benefit
Modular and compact design		
Compact size	Smallest frame size is only 4 in (93 mm) wide.	Optimum installation layout and efficient cabinet space
	More drives can be placed in the same cabinet.	usage.
		Space and cost savings.
Side-by-side mounting	Minimized cabinet wall space.	Space and cost savings.
	No need to remember air gaps between drives.	
Modular design	Many standard features and a wide range of options	Fits many application needs.
	allow different system configurations.	Offers flexibility in system design.
Optimal location of power	Top-down power flow in frames A to D and G1 to G2	Easy connection of power cables.
terminals	enables the most optimal cabinet layout in many cases.	Optimum installation layout and efficient cabinet space
		usage.
		Optimized EMC design.
Integrated brake chopper	Brake chopper as standard up to 30 hp (frames A to D)	Compact and cost-effective design.
	and a built-in option for other frame sizes.	
User interface and programming	ng	
Intuitive human-machine	Large alphanumeric display showing different assistants	Faster and more accurate drive configuration.
interface	and macros.	Optimal drive settings as assistants offer interactive help.
	Extremely easy to use and commission the drive.	
	DriveStudio PC-tool offers easy access to drive	
	parameter setting and start-up features.	
Drive programming and	Can replace relays and small PLCs with function block	Lower investment cost.
configuration	programming.	Higher flexibility in system design.
Memory unit for easy drive	Complete drive configuration and settings are stored in a	Drive functionality can be easily configured, modified or
management	separate memory unit.	updated with the memory unit.
	Power or control unit can be replaced without parameter	Offers quick and easy after-sales service.
	setting.	
Designed for reliability		
Robust main circuit design	Enhanced reliability.	Less process interruptions.
	Coated boards and long life time components.	Lower maintenance costs.
	Cooling supervision (depending on frame size).	
Extensive protection	Advanced thermal protection of the drive semiconductors	Higher process uptime.
	and motor.	Early warning of any production interruptions.
	Several adjustable protections for the drive and adjoining	
	equipment ensure a reliable operation.	
Maintenance assistant	Indicates preventive maintenance needs of drive, motor	Helps with maintenance schedules and cost control of
	or machine.	maintenance.
	User-set alarms and triggering limits.	Fewer unexpected process interruptions.
	Monitors running hours, cooling fan running hours,	
	number of relay switchings etc.	
Diagnostic assistant	Drive helps in locating failures or reasons for performance	Reduced process downtime.
	changes and suggests remedies.	Faster recovery to drives optimum performance.
Optimized use		
- p	Monitors used and saved energy, displayed in kWh,	Easy to check the return on investment.
Energy saving calculator	i Mornitors used and saved energy, displayed in kwin,	
	currency (\$ or Euros) or volume of CO ₂ emission.	,
Energy saving calculator	currency (\$ or Euros) or volume of CO ₂ emission.	
Energy saving calculator Load analyzer	currency ($\$$ or Euros) or volume of CO_2 emission. Shows the load profile of the drive.	Easy process analysis.
Energy saving calculator	currency (\$ or Euros) or volume of CO ₂ emission.	

Main features

Feature	Advantage	Benefit
Control and performance		
Compatible with AC induction and permanent magnet motors	Same drive can be used to control different motor types.	Savings in investment costs. Savings in spares stockholding.
Standard drive-to-drive link, configurable as Modbus link	No additional hardware needed for master-follower communication or Modbus. Galvanic isolation.	Lower investment cost. More reliable, disturbance-free isolation.
Different communication options	Flexibility with master communication - drive supports PROFIBUS, CANopen®, DeviceNet™, Modbus, EtherCAT, Modbus TCP and Ethernet / IP™ communication.	Drive can be applied to many existing processes.
Integrated safe torque-off function (up to SIL 3)	Safe torque-off (STO) is used to prevent unexpected start-up. High SIL class means high reliability of the safety function. Can also be used to implement Emergency Stop without contactors.	Enhances safety of the machines. Cost-effective and certified solution for safe machine maintenance. Fulfils new safety directives IEB 61508, IEC 62061 and EN ISO 13489-1.
Extensive configurable standard I/Os.	Optimized accessibility.	Lower cost. Fewer parts and installation work needed for cabinet assembly.
Optional I/O extensions	Plug-in analog and digital I/O extensions.	Extends drives' scope, performance and applications opportunities.
Direct torque control	Accurate, dynamic and static speed and torque control. Excellent process control even without pulse encoder. Power interruption ride-through using kinetic energy of load. Fast reaction to load or voltage variations. No shock torques. No torque ripple - minimized risk for torsional vibration. Less noise during motor operation. Output frequency up to 500 Hz. Enhanced motor identification at stand still.	Improves product quality, productivity and reliability. Lower investment cost. No unnecessary trips or process interruptions. Less maintenance. Suitable for use where audible noise is an issue. Applicable in high speed applications. Better process control due to more accurate identification. Can do motor identification without decoupling the load.
High overload and high starting torque	Smooth start without over-dimensioning the drive.	Longer motor and gear lifetime thereby reduced maintenance costs.
Made by ABB		
Global market leader in AC drives with long experience World wide service and support	Well proven, safe and reliable solutions. Application know-how. Professional support available around the world.	Highly reliable drives. High quality service and support wherever you need it.
network		

Technical data

ACS850	-	04	-	XXXX	-	2	+	XXXX
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Mains connection	
Supply voltage	3-phase 380 to 500 V AC +10 /-15%
	3-phase 200 to 240 V AC ± 10%
Frequency	50 to 60 Hz ± 5%
DC connection	
DC voltage level	485 to 675 V DC ± 10% (-5 types)
	270 to 324 V DC ± 10% (-2 types)
Charging circuit	Internal in frames A to D
	External in frames E0 to G2
Motor connection	
Motor types	AC induction motors and permanent magnet
	motors
Output frequency	0 to 500 Hz
Motor control	Direct torque control (DTC) or scalar control
Torque control:	Torque step rise time:
Open loop	<5 ms with nominal torque
Closed loop	<5 ms with nominal torque
	Non-linearity:
Open loop	± 4% with nominal torque
Closed loop	± 3% with nominal torque
Speed control:	Static accuracy:
Open loop	10% of motor slip
Closed loop	0.01% of nominal speed
	Dynamic accuracy:
Open loop	0.3 to 0.4% sec. with 100% torque step
Closed loop	0.1 to 0.2% sec. with 100% torque step
Braking power conne	ection
Brake chopper	Standard in frames A to D, built-in option in the
	other frame sizes

Operating conditions	
Degree of protection	IP20 according to EN 60529 (G frame IP00);
	Open type according to UL 508
Ambient temperature	14 to 131 °F / (-10 to +55 °C), derating above
	104 °F (40 °C)
	No frost allowed
Installation altitude	0 to 13000 ft (0 to 4000 m) (IT network:
	6560 ft (2000 m)), derating above 3280 ft
	(1000 m): 1% / 328 ft (100 m)
Relative humidity	Max. 95%, no condensation allowed
Climatic/	Class 3K3, 3C2 according to EN 60721-3-3.
environmental	Oil mist, formation of ice, moisture condensation,
conditions	water drops, water spray, water splashes and
	water jets are not permissible (EN 60204, Part 1)
Vibration	Class 3M4 according to EN 60721-3-3
EMC (According to	Categories C2 and C3 with optional filter
EN 61800-3)	(according to EN 61800-3)
Functional safety	Safe torque-off (STO according EN 61800-5-2)
	IEC 61508: SIL 3
	IEC 61511: SIL3
	IEC 62061: SILCL 3
	EN ISO 13849-1: PL e
	Certified by TÜV
Compliance	Frames A to D: CE, GOST R, UL, cUL, CSA,
	C-Tick
	Frames E0 to G: CE, GOST R; pending: UL,
	cUL, CSA, C-Tick

Brake chopper	Standard in frames A to D, built-in option in the
	other frame sizes

Brake resistor External resistor connected to drive

Feature / frame size	Α	В	С	D	E0	E	G	G1*	G2 *
Current and power		1			<u>'</u>	<u>'</u>			
Nominal current	3 to 8 A	10.5 to 18 A	25 to 50 A	61 to 94 A	103 to 144 A	166 to 290 A	430 to 720 A	387 to 680 A	710 to 875 A
Maximum current	4.4 to 10.5 A	13.5 to 21 A	33 to 66 A	78 to 124 A	138 to 170 A	202 to 348 A	588 to 1017 A	470 to 710 A	850 to 1100 A
Typical motor power in hp (230 V)	0.5 to 2 hp	3 to 5 hp	7.5 to 15 hp	20 to 30 hp	_	-	_	_	_
(480 V)	1.5 to 5 hp	5 to 10 hp	15 to 30 hp	40 to 60 hp	75 to 100 hp	125 to 200 hp	350 to 600 hp	300 to 550 hp	600 to 700 hp
Typical motor power in kW (230 V)	0.37 to 1.5 kW	2.2 to 4 kW	5.5 to 11 kW	15 to 22 kW	_	-	-	_	_
(400 V)	1.1 to 3 kW	4 to 7.5 kW	11 to 22 kW	30 to 45 kW	55 to 75 kW	90 to 160 kW	200 to 400 kW	200 to 355 kW	400 to 500 kW
(500 V)	1.5 to 4 kW	5.5 to 11 kW	15 to 30 kW	37 to 55 kW	55 to 90 kW	110 to 200 kW	250 to 500 kW	250 to 400 kW	500 to 560 kW
Brake chopper	•	•	•	•					
Brake resistor							•		
Input choke			•	•	•	•	•	•	•
EMC filter / C2							<u></u>	-	
EMC filter / C3								•	•
Mounting and cooling									
Air cooling	•	•	•	•	•	•	•	•	•
Side-by-side mounting	•	•	•	•	•	•	_	-	_
DIN rail mounting	•	•	_	_	-	-	_	_	_
Removable power connectors	•	•	_	_	_	-	_	_	_
Removable control connectors	•	•	•	•	•	•	•	•	•

lacktriangle = standard \Box = option, built-in \blacksquare = option, external - = not available * available during 2011

Ratings, types and dimensions

ACS850 - 04 - XXXX - 2 + XXXX

Ratings 200 to 240 V

Nominal	ratings	No-overlo	ad use	Light-duty	use		Heavy-du	ty use		Type designation	Frame size	
I _{2N} (A)	I _{Max} (A)	P _N (hp) U _{N = 230 V}	$P_{\rm N}$ (kW) $U_{\rm N=230V}$	I _{Ld} (A)	P_{Ld} (hp) $U_{N = 230 \text{ V}}$	P _{Ld} (kW) U _{N = 230 V}	I _{Hd} (A)	P_{Hd} (hp) $U_{N = 230 \text{ V}}$	P _{Hd} (kW) U _{N = 230 V}			
3	4.4	0.5	0.37	2.8	0.5	0.37	2.5	0.5	0.37	ACS850-04-03A0-2	Α	
3.6	5.3	0.75	0.55	3.4	0.75	0.55	3	0.5	0.37	ACS850-04-03A6-2	Α	
4.8	7	1	0.75	4.5	1	0.75	4	0.75	0.55	ACS850-04-04A8-2	Α	
6	8.8	1.5	1.1	5.5	1	1.1	5	1	0.75	ACS850-04-06A0-2	Α	
8	10.5	2	1.5	7.6	2	1.5	6	1.5	1.1	ACS850-04-08A0-2	Α	
10.5	13.5	3	2.2	9.7	3	2.2	9	2	1.5	ACS850-04-010A-2	В	
14	16.5	3	3	13	3	3	11	3	2.2	ACS850-04-014A-2	В	
18	21	5	4	16.8	5	4	14	3	3	ACS850-04-018A-2	В	
25	33	7.5	5.5	23	7.5	5.5	19	5	4	ACS850-04-025A-2	С	
30	36	10	7.5	28	10	7.5	24	7.5	5.5	ACS850-04-030A-2	С	
35	44	10	7.5	32	10	7.5	29	10	7.5	ACS850-04-035A-2	С	
44	53	15	11	41	15	11	35	10	7.5	ACS850-04-044A-2	С	
50	66	15	11	46	15	11	44	15	11	ACS850-04-050A-2	С	
61	78	20	15	57	20	15	52	15	11	ACS850-04-061A-2	D	
78	100	25	18.5	74	25	18.5	66	20	15	ACS850-04-078A-2	D	

Ratings 400 to 500 V

Nomina	al ratings	No-overl	oad use		Light-	duty use			Heavy	y-duty use	•		Type designation	Frame
I _{2N} (A)	I _{Max} (A)	P _N (hp) U _{N = 480 V}	P _N (kW) U _{N = 400 V}	P _N (kW) U _{N = 500 V}	I _{Ld} (A)	P _{Ld} (hp) U _{N = 480 V}	P _{Ld} (kW) U _{N = 400 V}	P _{Ld} (kW) U _{N = 500 V}	/ _{Hd} (A)	P _{Hd} (hp) U _{N = 480 V}	P _{Hd} (kW) U _{N = 400 V}	P _{Hd} (kW) U _{N = 500 V}		size
3	4.4	1.5	1.1	1.5	2.8	1	1.1	1.1	2.5	1	0.75	1.1	ACS850-04-03A0-5	Α
3.6	5.3	2	1.5	1.5	3.4	2	1.5	1.5	3	1.5	1.1	1.5	ACS850-04-03A6-5	Α
4.8	7	3	2.2	2.2	4.5	2	1.5	2.2	4	2	1.5	2.2	ACS850-04-04A8-5	Α
3	8.8	3	2.2	3	5.5	3	2.2	3	5	3	2.2	2.2	ACS850-04-06A0-5	Α
3	10.5	5	3	4	7.6	5	3	4	6	3	2.2	3	ACS850-04-08A0-5	Α
10.5	13.5	5	4	5.5	9.7	5	4	5.5	9	5	4	4	ACS850-04-010A-5	В
14	16.5	7.5	5.5 7.5	7.5	13	7.5	5.5	7.5	11	7.5	5.5 7.5	5.5	ACS850-04-014A-5	В
18	21	10	7.5	11	16.8	10	7.5	7.5	14	10	7.5	7.5	ACS850-04-018A-5	В
25	33	15	11	15	23	15	11	11	19	10	7.5	11	ACS850-04-025A-5	С
30	36	20	15	18.5	28	20	15	15	24	15	11	15	ACS850-04-030A-5	С
35	44	25	18.5	22	32	20	15	18.5	29	20	15	18.5	ACS850-04-035A-5	С
14	53	30	22	30	41	30	22	22	35	25	18.5	22	ACS850-04-044A-5	С
50	66	30	22	30	46	30	22	30	44	30	22	30	ACS850-04-050A-5	С
31	78	40	30	37	57	40	30	37	52	40	22	30	ACS850-04-061A-5	D
78	100	60	37	45	74	50	37	45	66	50	37	45	ACS850-04-078A-5	D
94	124	60	45	55	90	60	45	55	75	50	37	45	ACS850-04-094A-5	D
103	138	75	55	55	100	75	55	55	83	60	45	55	ACS850-04-103A-5	E0
44	170	100	75	90	141	100	75	90	100	75	55	55	ACS850-04-144A-5	E0
66	202	125	90	110	155	125	75	90	115	75	55	75	ACS850-04-166A-5	Е
202	282	150	110	132	184	150	90	110	141	100	75	90	ACS850-04-202A-5	Е
225	326	150	110	132	220	150	110	132	163	125	90	110	ACS850-04-225A-5	Е
260	326	200	132	160	254	200		160	215	150	110	132	ACS850-04-260A-5	Е
90	348	200	160	200	286	200	160	200	232	150	132	160	ACS850-04-290A-5	Е
130	588	350	200	250	425	350	200	250	340	250	160	200	ACS850-04-430A-5	G
521	588	450	250	355	516	450	250	355	370	300	200	250	ACS850-04-521A-5	G
602	840	500	315	400	590	500	315	400	477	400	250	315	ACS850-04-602A-5	G
393	1017	550	355	450	679	550	355	450	590 ¹⁾	500	315	400	ACS850-04-693A-5	G
'20	1017	600	400	500	704	600	400	500	635 ²⁾	500	355	450	ACS850-04-720A-5	G
387	470	300	200	250	377	300	200	250	300	200	160	200	ACS850-04-387A-5	G1*
160	533	350	250	315	450	350	250	315	355	250	200	250	ACS850-04-460A-5	G1*
558	640	450	315	355	550	450	315	355	414	350	200	250	ACS850-04-558A-5	G1*
380	710	500	355	400	664	500	355	400	477	400	250	315	ACS850-04-680A-5	G1*
710	850	600	400	500	700	600	400	500	566	450	315	400	ACS850-04-710A-5	G2*

Notes

- $^{1)}$ For ambient temperature of less than 95 °F (35 °C) , maximum overload is 150% of $l_{\rm Hd}.$ For ambient temperature of 104 °F (40 °C), maximum overload is 145% of $l_{\rm Hd}.$
- $^{2)}$ For ambient temperature of less than 86 °F (30 °C), maximum overload is 150% of $I_{\rm Hd}$. For ambient temperature of 104 °F (40 °C)0, maximum overload is 140% of $I_{\rm Hd}$.
- * Available during 2011.

Nominal ratings
I _{2N} Rated current available continuously without overloading at 104 °F (40 °C).
I_{max} Maximum output current. Available for 10 s at start, otherwise as long as allowed by
drive temperature. Note: max. motor shaft power is 150% P _{Hd} .
Typical ratings: No-overload use
$P_{\rm N}$ Typical motor power in no-overload use.
Light-duty use
Continuous current allowing 110% I _{Ld} for 1 min / 5 min at 104 °F (40 °C).
P _{Ld} Typical motor power in light-duty use.
Heavy-duty use
Continuous current allowing 150% I _{Hd} for 1 min / 5 min at 104 °F (40 °C).
P _{Hd} Typical motor power in heavy-duty use.
The current ratings are the same regardless of the supply voltage within one voltage range.

The ratings apply at 104 °F (40 °C) ambient temperature.

Ratings, types and dimensions

ACS850	-	04	-	XXXX	-	2	+	XXXX
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Cooling characteristics and noise levels

Power loss	Air flow	Noise level	Type designation	Frame size
BTU/hr) (Watts) Load 10	00% ft ³ /min (m ³ /h)	dBA		
J _N = 200 to 240 V		'	<u>'</u>	
312 (91)	14 (24)	47	ACS850-04-03A0-2	2 A
332 (97)		47	ACS850-04-03A6-2	2 A
390 (114)	14 (24)	47	ACS850-04-04A8-2	2 A
157 (134)	14 (24)	47	ACS850-04-06A0-2	2 A
526 (154)	14 (24)	47	ACS850-04-08A0-2	.
326 (183)	28 (48)	39	ACS850-04-010A-2	2 B
'33 (215)	28 (48)	39	ACS850-04-014A-2	
36 (274)	28 (48)	39	ACS850-04-018A-2	
109 (325)	84 (142)	71	ACS850-04-025A-2	
438 (421)		71	ACS850-04-030A-2	··· · ·····
507 (442)	84 (142)	71	ACS850-04-035A-2	*
576 (462)	118 (200)		ACS850-04-044A-2	
894 (555)	118 (200)	71	ACS850-04-050A-2	····
2492 (730)		70	ACS850-04-061A-2	
3034 (889)	171 (290)	70	ACS850-04-078A-2	···•
3597 (1054)	171 (290)	70	ACS850-04-094A-2	···•
$J_{\rm N}$ = 400 to 500 V	111 (200)	,10	7,100000 01 00 17 2	. ,0
340 (100)	14 (24)	47	ACS850-04-03A0-5	5 A
000 (400)	14 (24)	47	ACS850-04-03A6-5	··· · ·····
00 (400)	14 (04)	····· j ·····	ACS850-04-04A8-5	-
04 (126) 04 (148)	14 (24)	47	ACS850-04-06A0-5	
86 (172)	14 (24)	47	ACS850-04-08A0-5	··· · ·····
'22 (212)	28 (48)	39	ACS850-04-010A-5	
352 (250)	28 (48)		ACS850-04-014A-5	.
084 (318)	28 (48)	39	ACS850-04-018A-5	*
282 (375)	84 (142)		ACS850-04-025A-5	···•
654 (485)	84 (142)	71	ACS850-04-020A-5	····
750 (513)	84 (142)	71	ACS850-04-035A-5	-
846 (541)		71	ACS850-04-044A-5	*
2205 (646)	118 (200)	71	ACS850-04-050A-5	
2867 (840)		70	ACS850-04-061A-5	
3481 (1020)	171 (290)	70	ACS850-04-078A-5	
1096 (1200)	171 (290)	70	ACS850-04-094A-5	···•
1061 (1190)	99 (168)	65	ACS850-04-103A-5	-
915 (1440)	238 (405)	65	ACS850-04-144A-5	
621 (1940)	238 (405)	65	ACS850-04-166A-5	
884 (2310)	238 (405)	65	ACS850-04-202A-5	
9591 (2819)	238 (405)	65	ACS850-04-225A-5	···•
1126 (3260)	;====.\.:==/	65	ACS850-04-260A-5	
4335 (4200)	238 (405)	65	ACS850-04-290A-5	
23379 (6850)	718 (1220)	72	ACS850-04-430A-5	G
26621 (7800)	718 (1220)	72	ACS850-04-521A-5	G
27645 (8100)	718 (1220)	72	ACS850-04-602A-5	G
31058 (9100)	718 (1220)	72	ACS850-04-693A-5	G
33106 (9700)	718 (1220)	72	ACS850-04-720A-5	G

Cooling characteristics and noise level data for frames G1 and G2 will be available during 2011.

Dimensions

Dimonolono										
Frame size	Height 1)		Depth ^{2) 3)}		Width		Weight			
	in	mm	in	mm	in	mm	lb	kg		
A	14.3	364	7.8	197	3.7	93	7	3		
В	15.0	380	10.8	274	4.0	101	11	5		
С	22.3	567	10.9	276	6.5	166	35	16		
D	22.3	567	10.9	276	8.7	221	51	23		
E0	23.7	602	13.9	354	10.9	276	77	35		
E	27.6	700	17.4	443	12.3	312	147	67		
G ⁴⁾	61.6	1564	22.4	568	22.1	562	441	205		
G1*	62.5	1587	20.2	512	13.1	332	428 - 448	194 - 203		
G2*	68.4	1737	20.2	512	13.1	332	505	229		

Notes

All dimensions and weights are without options.

- $^{\mbox{\tiny 1)}}$ Height is the maximum measure without clamping plates.
- ²⁾ An additional 2 in (50 mm) should be reserved for feedback cabling if FEN-01, -11 or -21 options are used (except for frame G1 and G2 with integrated control unit).
- ³⁾ Assistant control panel adds 0.9 in (23 mm) in to the depth (except for frame G1 and G2 with integrated control unit).
- Frame G includes separately mounted control section, 12.8 in (325 mm) H x 4.5 in (114 mm) D x 3.7 in (94 mm) () W, 3 lb (1.3 kg) (except for frame G1 and G2 with integrated control unit).
- * Available during 2011.

Standard control program

Based on direct torque control technology, the ACS850 offers highly advanced features as standard. The ACS850 standard program provides solutions to virtually all AC drives applications such as mixers, separators, extruders and conveyors, to name a few.

Fast and easy commissioning

The ACS850 standard program offers flexibility and extensive parameter settings. It consists of a simple, readymade program that can easily be modified to meet specific application needs. Commissioning is also simplified by several software features that come standard with every drive.

Pre-programmed protection functions

A wide range of features provides protection for the drive, motor and the process.

- Ambient temperature
- DC overvoltage
- DC undervoltage
- Drive temperature
- Input phase loss
- Overcurrent
- Power limits
- Short circuit

Furthermore the standard control program offers an integrated emergency stop and supports the functionality of prevention of unexpected start-up.

Programmable protection functions

- Adjustable power limits
- Control signal supervision
- Critical frequencies lock-out
- Current and torque limits
- Earth fault protection
- External fault
- Motor phase loss
- Motor stall protection
- Motor thermal protection
- Motor underload protection
- Panel loss

Program customization

In addition to standard control program functionalities, ACS850 offers, function block programming, which makes it possible to replace relays or even a PLC.

Removable memory unit

A removable memory unit provides easy maintenance by storing the complete firmware, including all user settings and motor data. Thus, if the power unit or control unit is replaced, the drive can be re-commissioned without any reprogramming, just move the memory unit.

- Stores the drive software and parameter settings
- Fast and easy recommissioning
- Enables software and parameter configuration at workshop instead of doing it on-site



Standard software features

ACS850 drives have many features to enhance their reliability and durability as well as the easiness of use. Among those, several macros for parameter settings and several advanced functions such as short and long parameter menus, input and output mapping and changed parameters list, making the drive easy to use.

All these functions can be accessed either via the user-friendly assistant control panel or DriveStudio PC tool.

Macros

Several macros which have pre-set, application-specific parameter settings are available as standard in each drive. These pre-programmed parameter settings enable fast and easy commissioning by adjusting all the relevant parameters in just a couple of clicks.

Start-up assistant

The intelligent and intuitive start-up assistant allows first-time users to quickly get up-to-speed and customize the drive according to their needs. This is complemented by a built-in help function to make parameter-by-parameter setting easy. This way the drive can be quickly commissioned, even without manuals.



Maintenance assistant

The maintenance assistant reminds the user about the drive's preventive maintenance schedule or routine, or that of its associated components such as motor, cabinet air inlet filters and input contactors. It reminds users of planned maintenance needs based on running hours, operating hours or relay switching to reduce unplanned process interruptions.

Diagnostic assistant

Each ACS850 drive is equipped with a diagnostic assistant that helps in locating the cause of any disturbance to the drive and even suggests possible remedies. This reduces process downtime by making repair or adjustments quicker and easier.

Energy saving features

- A calculator showing the used and saved energy, displayed in kWh, currency (€ or \$) or volume of CO₂ emission. Data is calculated by reference values stored in the drive by the user.
- An energy efficiency optimizer that adjusts the motor flux in such a way that the total efficiency is maximized.
- A load analyzer showing the load profile of the drive.

Short/long menus

The user interface can be configured so that it displays only the most common parameters. This short menu allows users to quickly access the parameters they need without having to go through all the drive's parameters.

A long menu is available, displaying a complete list of parameters for a more advanced configuration.

Input and output mapping

This functionality allows the user to easily go through the input and output configuration of the drive.

List of changed parameters

This feature allows users to go through the list of changed parameters. This way, the user does not have to go through all the drive's parameters making it quick to identify the ones recently modified.

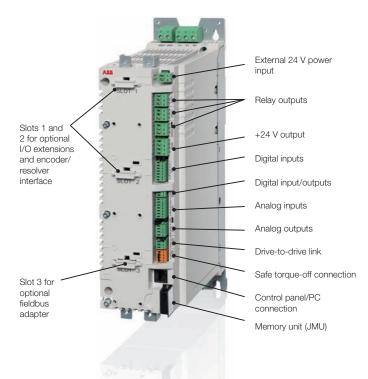
Standard I/O

ACS850 - 04 - XXXX - 2 + XXXX

Standard I/O connections

ACS850 drives have one of the most extensive offering of standard I/Os on the market. Analog and digital I/O channels are used for different functions such as control, monitoring and measurement purposes (eg, motor temperature).

- Control voltage supply: external supply (24 V DC) input for the control unit
- Digital I/O: 6 x DI, 2 x DI/O (can be used also for pulse train inputs or outputs, max 32 kHz), 3 x RO
- Analog I/O: 2 x AI (mA or V), 2 x AO (mA)
- Thermistor input: motor thermistor (PTC)
- Start interlock: drive interlock input
- Embedded Modbus link as standard, galvanically isolated for trouble-free operation and can be alternatively configured as a high speed drive-to-drive link for masterfollower operation
- Safe torque-off (STO): designed for Safety Integrity Level 3 (SIL 3) according to IEC 61508
- Control panel connection: PC tools and control panel connection (RJ45)
- Memory unit connection: complete drive configuration and settings are stored in the removable memory unit



Control unit

The control unit of the ACS850 consists of various control connections, which can be configured as required by the customer application.

External power input 24 V DC, 1.6 A GND 2 XR01, XR02, XR03 Relay output R01 [Ready] SO V DC C COM 2 COM 3 C			XPOW	
Relay output RO1 [Ready]		+24VI	1	
Relay output RO1 [Ready]	24 V DC, 1.6 A		2	
250 V AC / 30 V DC 2 A Relay output RO2 2 SO V AC / 30 V DC 2 A Relay output RO3 2 SO V AC / 30 V DC 2 A Ro 3 Relay output RO3 2 SO V AC / 30 V DC 2 A Ro 6 Relay output RO3 2 SO V AC / 30 V DC 2 A RO 7 COM 8 B 2 A RO 7 COM 8 B 2 A RO 9 RO 8 Relay output RO3 2 SO V AC / 30 V DC 2 A RO 9 RO 8 Relay output RO3 2 SO V AC / 30 V DC 2 A RO 9 RO 8 Relay output RO3 2 SO V AC / 30 V DC 2 A RO 9 RO 8 Relay output RO3 2 SO V AC / 30 V DC 2 A RO 9 RO 8 B 2 A RO 9 RO 8 Relay output RO3 2 SO V AC / 30 V DC 2 A RO 9 RO 8 Relay output RO3 2 SO V AC / 30 V DC 2 A RO 9 RO 8 Relay output RO3 2 SO V AC / 30 V DC 2 A RO 8 Relay output RO3 2 SO V AC / 30 V DC 2 A RO 8 Relay output RO3 2 SO V AC / 30 V DC 2 A RO 8 B 8 DI			2, XRO3	
NC 3 NC 3 Relay output RO2 NO 4 COM 5 COM 6 COM 8 COM 6			1 -	
Relay output RO2				
250 V AC / 30 V DC 2 A			=	
2 A				
Relay output RO3				
250 V AC / 30 V DC 2 A NC 9				
2 A				
**24 V DC*			-	
+24 ∨ DC* Digital input ground +24 ∨ DC* Digital input/output ground Ground selection jumper Digital input DI1 [Stop/Start] DI1 1 1 1 1 1 1 1 1 1		INC	Ü	
Digital input ground	+24 \/ DC*	+24VD	$\overline{}$	
#24 V DC* Digital input/output ground Ground selection jumper Vabruary V				
Digital input/output ground Ground selection jumper XDI Digital input DI1 [Stop/Start] Digital input DI2 DI2 2 Digital input DI3 [Reset] Digital input DI4 DI5 DI5 DI6 5 Digital input DI6 or thermistor input Digital input DI6 or thermistor input Digital input DI6 DI6 6 Start interlock (0 = Stop) Digital input/output DIO1 [Output: Ready] Digital input/output DIO2 [Output: Running] DiO2 2 XAI Reference voltage (+) Reference voltage (-) Ground Analog input Al1 (Current or voltage, selectable by jumper Al1) [Speed reference 1] Analog input Al2 (Current or voltage, selectable by jumper Al2) Al1 current/voltage selection jumper Al2 current/voltage selection jumper Al2 current/voltage selection jumper Al2 current/voltage selection jumper Al2 Analog output AO1 [Current %] Analog output AO2 [Speed %] ANO2- XAO Analog output AO2 [Speed %] ANO2- XDDIO XAI Reference voltage (+) ANO1- ANO2- ANO3- AN				_
Ground selection jumper XDI Digital input DI1 [Stop/Start] Digital input DI2 DI2 2 Digital input DI3 [Reset] Digital input DI4 DI4 DI5 DI5 DI5 5 Digital input DI6 or thermistor input DI6 6 Start interlock (0 = Stop) Digital input/output DIO1 [Output: Ready] Digital input/output DIO2 [Output: Running] DIO2 2 XAI Reference voltage (+) Reference voltage (-) Ground Analog input AI1 (Current or voltage, selectable by jumper AI1) [Speed reference 1] Analog input AI2 (Current or voltage, selectable by jumper AI2) AI1 current/voltage selection jumper AI2 current/voltage selection jumpe				
Digital input DI1 [Stop/Start]		Biodita	\vdash	
Digital input DI2 DI2 2 Digital input DI3 Reset DI3 3 Digital input DI4 DI4 4 DI4 4 DI5 5 Digital input DI6 DI5 5 Digital input DI6 or thermistor input DI6 6 Start interlock (0 = Stop) DIIL A XDIO XDIO Digital input/output DIO1 Output: Ready DIO2 2 XAI Reference voltage (+) +VREF 1 +VREF 1 AGND 3 Analog input AI1 (Current or voltage, selectable by jumper AI1) Speed reference 1 AI1 AI1 5 Analog input AI2 (Current or voltage, selectable by jumper AI2) AI2 AI2 AI1 Current/voltage selection jumper AI2 AI1 AI2 AI1 AI2 AI1 AI2 AII AI2 AII A	around solootion jumpor		XDI	
Digital input DI2 DI2 2 Digital input DI3 Reset DI3 3 Digital input DI4 DI4 4 DI4 4 DI5 5 Digital input DI6 DI5 5 Digital input DI6 or thermistor input DI6 6 Start interlock (0 = Stop) DIIL A XDIO XDIO Digital input/output DIO1 Output: Ready DIO2 2 XAI Reference voltage (+) +VREF 1 +VREF 1 AGND 3 Analog input AI1 (Current or voltage, selectable by jumper AI1) Speed reference 1 AI1 AI1 5 Analog input AI2 (Current or voltage, selectable by jumper AI2) AI2 AI2 AI1 Current/voltage selection jumper AI2 AI1 AI2 AI1 AI2 AI1 AI2 AII AI2 AII A	Digital input DI1 [Stop/Start]	DI1	1	- /-↓
Digital input DI3 [Reset] DI3 3		_		
Digital input DI4 Digital input DI6 Digital input DI6 or thermistor input DI6 Digital input DI6 or thermistor input DI6 Digital input DI6 or thermistor input DIIL A DIIIL A DIGITAL DIO DIO1 1 Digital input/output DIO1 [Output: Ready] DIO2 XAI Reference voltage (+) Reference voltage (+) Reference voltage (-) Ground AGND Analog input Al1 (Current or voltage, selectable by jumper Al1) [Speed reference 1] Analog input Al2 (Current or voltage, selectable by jumper Al2) Al1- Al1 current/voltage selection jumper Al2 current/voltage selection jumper Al2 current/voltage selection jumper Al2 current/voltage selection jumper Al2 current/voltage selection jumper Al3 AO1- Analog output AO1 [Current %] AO2- ANAO Analog output AO2 [Speed %] AO2- AO2- AO2- AO2- AO2- AO3 AO2- AO2- AO3 AO2- AO3 AO3 AO4 AO4 AO5 BGND A SXTO OUT1 Divive-to-drive link termination jumper SXBO OUT1 I OUT2 Closed for the drive to start. IN1			3	
Digital input DI6 or thermistor input Start interlock (0 = Stop) Digital input/output DIO1 [Output: Ready] Digital input/output DIO2 [Output: Running] DIO2 Efference voltage (+) Reference voltage (-) Ground Analog input Al1 (Current or voltage, selectable by jumper Al1) [Speed reference 1] Analog input Al2 (Current or voltage, selectable by jumper Al2) Al1 current/voltage selection jumper Al2 current/voltage selection jumper Al3 current/voltage selection jumper Al4 current/voltage selection jumper Al7 A01- A01- A02- A02- A02- A02- Drive-to-drive link termination jumper Safe torque-off. Both circuits must be closed for the drive to start. DIO1 AD1 AD1 AD2 AD3 AD4 AD5 AD7 AD7 AD7 AD7 AD7 AD7 AD7			4	
Start interlock (0 = Strop) Start interlock (0 = Strop) Digital input/output DIO1 [Output: Ready] Digital input/output DIO2 [Output: Running] Digital input/output DIO2 [Output: Running] Reference voltage (+) Reference voltage (-) Referenc	Digital input DI5	DI5	5	
Start interlock (0 = Stop) DIIL A XDIO Digital input/output DIO1 [Output: Ready] DiO2 2 Reference voltage (+) Reference voltage (-) Ground Analog input Al1 (Current or voltage, selectable by jumper Al1) [Speed reference 1] Analog input Al2 (Current or voltage, selectable by jumper Al2) Al1 current/voltage selection jumper Al2 current/voltage selection jumper Al3 current/voltage selection jumper Al4 current/voltage selection jumper Al7 AO1- Analog output AO1 [Current %] AO2- Analog output AO2 [Speed %] AO2- XD2D Drive-to-drive link termination jumper Safe torque-off. Both circuits must be closed for the drive to start. IN1 3 IN2 AII IN1 3 IN2 AAI AVAI AVI AVI AVI AVI AVAI AVI AVI AVAI AVI AVAI AVI AVI AVAI AVAI AVI AVAI AVI AVI AVAI AVI AVAI AVI AVAI AVI AVI AVAI AVAI AVI AVI AVAI AVI AVI AVAI AVI AVI AVAI AVI AVAI AVI AVAI AVI AVI AVI AVAI AVI AVAI AVI AVAI AVI AVAI AVI AVI AVAI AVI AVI AVAI AVI A	Digital input DI6 or thermistor input	DI6	6	
Digital input/output DIO1 [Output: Ready] Digital input/output DIO2 [Output: Running] Reference voltage (+) Reference voltage (-) R		DIIL	Α	
Digital input/output DiO2 [Output: Running]			XDIO	
Analog output AO1 [Current %]	Digital input/output DIO1 [Output: Ready]	DIO1	1	⊗
Accord A	Digital input/output DIO2 [Output: Running]	DIO2	2	⊗
Reference voltage (-)			XAI	
AGND 3 AGND 3 AGND 3 Analog input Al1 (Current or voltage, selectable by jumper Al1) (Speed reference 1) Al1- 5 Al2- 6 Al2- 7 Al1 current/voltage selection jumper Al2 Al2- 7 Al1 current/voltage selection jumper Al2 Al2- 7 Al2 current/voltage selection jumper Al2 Al2- Al2 Al2- Al2 Al2 Al2- Al2 Al2- Al2				
Analog input Al1 (Current or voltage, selectable by jumper Al1) [Speed reference 1] Analog input Al2 (Current or voltage, selectable by jumper Al1) [Speed reference 1] Analog input Al2 (Current or voltage, selectable by jumper Al2) Al2- 7 Al1 current/voltage selection jumper Al2 current/voltage selection jumper Al2 current/voltage selection jumper Analog output AO1 [Current %] Analog output AO2 [Speed %] Analog output AO2 [Speed %] AO2- 4 AO2- 4 AD2- 4				
jumper Al1) [Speed reference 1] Al1- Analog input Al2 (Current or voltage, selectable by jumper Al2) Al2- Al2- Al1 current/voltage selection jumper Al2 Al2 current/voltage selection jumper Al2 Analog output AO1 [Current %] AO1- Analog output AO2 [Speed %] AO2- Analog output AO2 [Speed %] AO2- Drive-to-drive link termination jumper T Drive-to-drive link. B 1 A 2 BGND 3 SSTO OUT1 1 Safe torque-off. Both circuits must be closed for the drive to start. IN1 3 IN2 4	Ground			7 I
Analog input Al2 (Current or voltage, selectable by jumper Al2) Al1 current/voltage selection jumper Al2 xAO Analog output AO1 [Current %] AO1+ AO1+ AO2+ AO2+ AO2- AO2- AO2- TDrive-to-drive link termination jumper B 1 Drive-to-drive link. A 2 BGND 3 XSTO OUT1 Safe torque-off. Both circuits must be closed for the drive to start. IN1 IN2 Al2- IIN1 IN1 IN2 Al2- IIN1 IN2 Al2- IIN1 IN2 Al2- IIN1 IN2 Al2- IIN1 IN1 IN2 Al2- IIN1 IIN1 IIN1 IIN2 Al2- IIN1 IIN1 IIN2 Al2- IIN1 IIN1 IIN2 Al2- IIN1 IIN1 IIN1 IIN2 Al2- IIN1 IIN1 IIN1 IIN1 IIN2 Al2- IIN1 IIN1			_	+
Jumper AI2 AI2- 7				
Al1 current/voltage selection jumper Al2 current/voltage selection jumper Al2 current/voltage selection jumper Analog output AO1 [Current %] Analog output AO2 [Speed %] Analog output AO2 [Speed %] AO2- XD2D Drive-to-drive link termination jumper Drive-to-drive link. B		_		
Al2 current/voltage selection jumper Al2 XAO Analog output AO1 [Current %] Analog output AO2 [Speed %] Analog output AO2 [Speed %] AO2+ XD2D Drive-to-drive link termination jumper Drive-to-drive link. B		Al2-	_	
Analog output AO1 [Current %] AO1+ AO1- AO2- AO2- AO2- AO2- AO2- Drive-to-drive link termination jumper Drive-to-drive link. A 2 BGND 3 XSTO OUT1 1 OUT2 2 closed for the drive to start. IN1 3 IN2 4				
Analog output AO1 [Current %] AO1+ AO1- AO1- AO2+ AO2+ AO2- AO2- AO2- TO AO2- AO	Al2 current/voltage selection jumper			
Analog output AO1 [Current %] AO1- 2 AO2+ 3 AO2- 4 XD2D Drive-to-drive link termination jumper Drive-to-drive link. B 1 A 2 BGND 3 XSTO OUT1 1 OUT2 2 closed for the drive to start. IN1 3 IN2 4		401.	$\overline{}$	_
Analog output AO2 [Speed %] AO2+ AO2- 4 XD2D Drive-to-drive link termination jumper Drive-to-drive link. B	Analog output AO1 [Current %]			
Analog output AO2 [Speed %] AO2- XD2D Drive-to-drive link termination jumper T Drive-to-drive link. A 2 BGND 3 XSTO OUT1 1 OUT2 2 closed for the drive to start. IN1 3 IN2 4				$\overline{}$
Drive-to-drive link termination jumper	Analog output AO2 [Speed %]			()
Drive-to-drive link termination jumper		AUZ-		
B	Drive-to-drive link termination jumper			
A 2 BGND 3 XSTO	Drive to drive with terrimation jumper	B		
BGND 3 XSTO	Drive-to-drive link.			
XSTO				
Safe torque-off. Both circuits must be closed for the drive to start. OUT1 1 OUT2 2 IN1 3 IN2 4		20.12		
Safe torque-off. Both circuits must be closed for the drive to start. OUT2 IN1 IN2 4		OUT1		
closed for the drive to start. IN1 3 IN2 4	Safe torque-off. Both circuits must be			
IN2 4			3	
Control panel connection				
	Control panel connection			

^{*}Total maximum current: 200 mA

Options Control and communication modules

ACS850	_	04	-	XXXX	-	2	+	XXXX
						5		

Optional I/O

The optional I/O extension modules provide additional connectivity possibilities for ACS850 drives. Extensions include analog and digital modules and speed feedback interface modules which are mounted in the slots on the ACS850 control board. The control board has two slots available for I/O extension modules. Additionally, there is a third slot available for fieldbus adapter modules.



Fieldbus adapter modules

A wide range of fieldbus protocols are supported to enable the ACS850 to connect to major automation systems. Fieldbus adapter modules allow manufacturing flexibility, reduced installation and engineering effort via:

- Drive control
- Drive monitoring
- Drive diagnostics (via alarms, limit and fault words)
- Drive parameter handling

Options	Option codes	Data	Install in				
Analog and	digital extension mod	lules					
FIO-01	+L501	4 x DI/O, 2 x RO					
FIO-11	+L500	3 x AI (mA/V), 1 x AO (mA), 2 x DI/O	Slot 1 or 2				
FIO-21	+L519	1 x AI (mA/V), 1 x AO (mA), 1 x DI, 2 x RO					
Feedback in	terface modules						
FEN-01	+L517	2 inputs (TTL incremental encoder), 1 output 1)					
FEN-11	+L518	2 inputs (SinCos absolute, TTL incremental encoder), 1 output 1)	Slot 1 or 2				
FEN-21	+L516	+L516 2 inputs (Resolver, TTL incremental encoder), 1 output 1)					
FEN-31	+L502	1 input (HTL incremental encoder), 1 output					
Fieldbus ada	apter modules						
FPBA-01	+K454	PROFIBUS-DP, DPV0/DPV1					
FCAN-01	+K457	CANopen®					
FDNA-01	+K451	DeviceNet™	Slot 3				
FENA-01	+K466	EtherNet/IP™, Modbus TCP, PROFINET IO ²⁾	SIOU 3				
FSCA-01	+K458	Modbus RTU					
FECA-01	+K469	EtherCAT®					

¹⁾ When this module is used, the lower part of the control unit cover cannot be used.

²⁾ Available during 2011.

Options Control panel

ACS850 XXXX **XXXX** 2

Assistant control panel

The assistant control panel features a multilingual alphanumeric display for easy drive configuration. It is an ideal tool for service engineers, providing the following features:



- A large alphanumeric display
- Easy to navigate
- Soft and convenient keys
- Local control keys (start/stop/reference)
- Parameter setting and monitoring
- Status and history data
- Real-time clock
- Assisting functionalities like
 - Start-up assistant
 - Maintenance assistant
 - Diagnostic assistant



Assistant control panel options

There are various cover assembly options for the ACS850. The cover is mounted on the drive depending on the specific need of the customer application.

Standard control unit cover

Comes as standard without assistant control panel and holder.



Control unit cover with panel holder (+J414)

Includes control unit cover with panel holder, panel cover and internal interface cable.



Control unit cover with assistant control panel (+J400)

Includes assistant control panel, control unit cover with panel holder and internal interface cable.



Door mounting kit with assistant control panel (+J410)

Includes assistant control panel and panel holder for cabinet door mounting, with IP54 kit and 10 ft (3 m) cable.



Options FMC filters

ACS850	-	04	-	XXXX	-	2	+	XXXX
						5		

Electromagnetic Compatibility (EMC) and modules

The electrical/electronic equipment must be able to operate without problems within an electromagnetic environment. This is called immunity. The ACS850 is designed to have adequate immunity against interference from other equipment. Likewise, the equipment must not disturb or interfere with any other product or system within its locality. This is called emission. Each ACS850 model can be equipped with a built-in filter to reduce high frequency emission.

EMC standards

The EMC product standard (EN 61800-3 (2004)) covers the specific EMC requirements stated for drives (tested with motor and cable) within the EU.

EMC standards such as EN 55011, or EN 61000-6-3/4, are applicable to industrial and domestic equipments and systems including drive components inside. Drive units complying with requirements of EN 61800-3 are compliant with comparable categories in EN 55011 and EN 61000-6-3/4, but not necessarily vice versa. EN 55011 and EN 61000-6-3/4 do not specify cable length nor require a motor to be connected as a load. The emission limits are comparable according to the following EMC standards table.

1st environment vs 2nd environment

1st environment (category C1 to C2)

1st environment includes domestic premises. It also includes establishments directly connected without intermediate transformer to a low-voltage power supply network which supplies buildings used for domestic purposes.

2nd environment (category C3 to C4)

2nd environment includes all establishments other than those directly connected to a low-voltage power supply network which supplies buildings used for domestic purposes.

Selecting an EMC filter

The following table (below) gives the correct filter selection.

EMC standards

EN61800-3 (2004) product standard	EN 55011, product family standard	EN 61000-6-4, generic	EN 61000-6-3, generic emission
	for industrial, scientific and medical	emission standard for industrial	standard for residential, commercial
	(ISM) equipment	environments	and light-industrial environment
Category C1	Group 1	Not applicable	Applicable
(1st environment)	Class B		
Category C2	Group 1	Applicable	Not applicable
(1st environment)	Class A		
Category C3	Group 2	Not applicable	Not applicable
(2 nd environment)	Class A		
Category C4	Not applicable	Not applicable	Not applicable
(2 nd environment)			

EMC category / frame	Option code	A to B	C to D	E0 to E	G
C3 filter, earthed/unearthed network *	+E210	_	_		
C3 filter earthed network only *	+E200	1)		-	-
C2 filter, earthed network only *	+E202	_	_		_
C2 filter, earthed network only *		2)	2)	-	_

 \square = option, built-in \blacksquare = option, external - = not available

EMC category for frame G1 will be released during 2011. In frame G2 EMC category 3 comes as standard.

- 1) External, plug-in
- 2) External accesory, no plus code
- Max. cable length 328 ft (100 m)

Options Mains circuit



Mains chokes

Mains chokes are typically used to reduce harmonics in the mains current. Frames C to G2 are equipped with builtin choke as standard. For frames A and B, the ACS850 drives do not necessarily need a separate mains choke for operation. If, however, separate mains choke are needed, they are available to meet different system design requirements.

Frame	Drive type	Туре	Dimension	าร		Weight				
size	designation		Width		Length		Depth			
			in	mm	in	mm	in	mm	lb	kg
А	ACS850-04-03A0-5	CHK-01	4.72	120	5.75	146	3.11	79	4.0	1.8
Α	ACS850-04-03A6-5	CHK-01	4.72	120	5.75	146	3.11	79	4.0	1.8
Α	ACS850-04-04A8-5	CHK-02	5.91	150	6.89	175	3.39	86	8.4	3.8
Α	ACS850-04-06A0-5	CHK-02	5.91	150	6.89	175	3.39	86	8.4	3.8
В	ACS850-04-08A0-5	CHK-02	5.91	150	6.89	175	3.39	86	8.4	3.8
В	ACS850-04-010A-5	CHK-03	5.91	150	6.89	175	3.39	100	11.9	5.4
В	ACS850-04-014A-5	CHK-03	5.91	150	6.89	175	3.39	100	11.9	5.4
В	ACS850-04-018A-5	CHK-04	5.91	150	6.89	175	3.39	100	11.5	5.2

Resistor braking

Depending on the application, an external braking resistor may be needed to dissipate the generated kinetic energy thermally. For this, ACS850 uses its braking chopper and external braking resistor.

Brake chopper

The ACS850 series has built-in brake choppers in frames A to D (up to 60 hp (45 kW) at 480 V) as standard. Above this, brake choppers are available as built-in options.

Brake control

Brake control keeps the intermediate circuit voltage level to set limits, detects possible failures like brake chopper or resistor overtemperature, braking chopper, resistor or resistor cable short circuit.

Brake resistor

Preselected brake resistors are separately available for all ACS850 types. Resistors include intergrated thermal sensor as standard. Resistors other than standard offering may be used providing the specified resistance value is not decreased, and the heat dissipation capacity of the resistor is sufficient for the drive application.

For ACS850 drives, no separate fuses in the brake circuit are required if the following conditions are met:

- The ACS850 mains cable is protected by fuses
- No mains cable/fuse overrating takes place

ACS850 drives

Three phase 380-480 V applications, stopping duty only

Standard Enclosed Resistor packages 1

		DutyCycle=3sec or	n/27sec d	off		DutyCycle=10sec on/50sec off						
Drive P/N	HP											
ACS850-04-	ND	Resistor Part No.	Ohms	Watts	Dimensions	Resistor Part No.	Ohms	Watts	Dimensions			
06A0-5	3	P14494-61	120	300	12Wx5Dx5H	P14494-61	120	300	12Wx5Dx5H			
08A0-5	5	P14494-61	120	300	12Wx5Dx5H	ABB-48431-110	120	600	12Wx7Dx5H			
010A-5	5	ABB-48431-050	80	400	12Wx5Dx5H	ABB-48431-052	80	800	12Wx7Dx5H			
014A-5	7,5	ABB-41152	45	600	12Wx7Dx5H	P14494-25	45	800	12Wx7Dx5H			
D18A-5	10	ABB-41152	45	600	12Wx7Dx5H	P14494-26 45		1260	12Wx10Dx5H			
025A-5	15	ABB-48431-002	22	819	12Wx7Dx5H	ABB-48431-004	22	1408	12Wx13Dx5H			
030A-5	20	ABB-41154	22	900	12Wx10Dx5H	ABB-48431-005	22	1862	12Wx16Dx5H			
035A-5	20	ABB-48431-003	22	1140	12Wx10Dx5H	ABB-44472	22	1904	12Wx16Dx5H			
044A-5	30	ABB-48431-030	13	1433	12Wx13Dx5H	ABB-48431-033	13	3328	19Wx10Dx5H			
050A-5	30	ABB-48431-030	13	1433	12Wx13Dx5H	ABB-48431-033	13	3328	19Wx10Dx5H			
061A-5	40	ABB-48431-031	13	1872	12Wx16Dx5H	ABB-48431-033	13	3328	19Wx10Dx5H			
 078A-5	50	ABB-48431-033	13	3328	19Wx10Dx5H	ABB-44495	13	4153	26.5Wx10Dx5H			
094A-5	60	ABB-48431-033	13	3328	19Wx10Dx5H	ABB-48431-036	13	6292	26.5Wx13Dx5H			
103A-5	75	ABB-41170	8	4600	26.5Wx10Dx5H	ABB-48431-120	8	6272	26.5Wx16Dx5H			
144A-5	100	ABB-41161	6	4600	26.5Wx10Dx5H	ABB-44499	6,1	9444	28Wx10Dx10H			
166A-5	125	ABB-48431-183	4,3	6209	26.5Wx13Dx5H	ABB-48431-184	4,3	10750	28Wx10Dx10H			
202A-5	150	ABB-44479	4,26	9872	26.5Wx16Dx5H	ABB-44480	4,26	11696	28Wx10Dx10H			
225A-5	150	ABB-44479	4,26	9872	26.5Wx16Dx5H	ABB-44480	4,26	11696	28Wx10Dx10H			
260A-5	200	ABB-44479	4,26	9872	26.5Wx16Dx5H	ABB-48431-185	4,3	17067	28Wx13Dx10H			
200/10	: 200	:	•	•	: 20.00001000011	:			EZOVATODATOTI			
Duine D/N	НР	DutyCycle=3sec or	n/2/sec 0	Off 		DutyCycle=10sec	on/50sec	Off				
Orive P/N												
ACS850-04-	ND	Resistor Part No.	Ohms	Watts	Dimensions	Resistor Part No.	Ohms	Watts	Dimensions			
290A-5	200	ABB-48431-271	2,9	14210	28Wx10Dx10H	ABB-48431-272	2,9	16313	28Wx10Dx10H			
	300	ABB-48431-330	2,2	14080	28Wx16Dx10H	ABB-48431-332	2,2	26620	30Wx18Dx24H			
430A-5	350	ABB-48431-331	2,2	17820	28Wx13Dx10H	ABB-48431-333	2,2	31680	30Wx18Dx24H			
	400	ABB-48431-392	1,7	17000	28Wx13Dx10H	ABB-48431-394	1,7	30983	30Wx18Dx32H			
521A-5	450	ABB-48431-393	1,7	24480	30Wx18Dx16H	ABB-44508	1,72	43916	30Wx18Dx32H			
602A-5	500	ABB-48431-450	1,35	24604	30Wx18Dx16H	ABB-48431-453	1,35	46204	30Wx18Dx32H			
693A-5	550	ABB-48431-512	1	27225	30Wx18Dx24H	ABB-48431-516	1	50625	30Wx18Dx24H			
720A-5	600	ABB-48431-512	1	27225	30Wx18Dx24H	ABB-48431-516	1	50625	30Wx18Dx24H			
		DutyCycle=30sec	DutyCycle=30sec on/180sec off					DutyCycle=60sec on/180sec off				
Drive P/N	HP											
ACS850-04-	ND	Resistor Part No.	Ohms	Watts	Dimensions	Resistor Part No.	Ohms	Watts	Dimensions			
06A0-5	3	ABB-48431-110	120	600	12Wx7Dx5H	P14494-17	150	900	12Wx10Dx5H			
08A0-5	5	ABB-48431-110	120	600	12Wx7Dx5H	P14494-18	150	1200	12Wx13Dx5H			
010A-5	5	ABB-48431-052	80	800	12Wx7Dx5H	ABB-48431-053	80	1600	12Wx13Dx5H			
014A-5	7,5	P14494-26	45	1260	12Wx10Dx5H	P14494-27	45	1920	12Wx16Dx5H			
D18A-5	10	P14494-26	45	1260	12Wx10Dx5H	P14494-28	45	2450	19Wx13Dx5H			
025A-5	15	ABB-48431-005	22	1862	12Wx16Dx5H	ABB-48431-008	22	3168	19Wx13Dx5H			
030A-5	20	ABB-48431-007	22	2426	19Wx10Dx5H	ABB-48431-009	22	5632	26.5Wx10Dx5H			
035A-5	20	ABB-44515	22	2910	19Wx13Dx5H	ABB-48431-009	22	5632	26.5Wx10Dx5H			
044A-5	30	ABB-44474	13	3558	19Wx10Dx5H	ABB-48431-036	13	6292	26.5Wx13Dx5H			
	30	ABB-44474	13	3558	19Wx10Dx5H	ABB-48431-036	13	6292	26.5Wx13Dx5H			
050A-5	40	ABB-44517	13,3	5093	26.5Wx13Dx5H	ABB-48431-037	13	8125	26.5Wx16Dx5H			
		··· ! ·····	13	6292	26.5Wx13Dx5H	ABB-48431-038	13	11700	28Wx13Dx10H			
061A-5	·· } ·····	: ABB-48431-036				ABB-48431-038	13	11700	28Wx13Dx10H			
061A-5 078A-5	50	ABB-48431-036 ABB-48431-037	13	8125	: 26.5Wx16Dx5H			,	ESTATORATOR			
061A-5 078A-5 094A-5	50 60	ABB-48431-037	13 8	8125 11552	26.5Wx16Dx5H		8	15488	28\Wy16Dv10H			
061A-5 078A-5 094A-5 103A-5	50 60 75	ABB-48431-037 ABB-48431-122	8	11552	28Wx10Dx10H	ABB-48431-123	8	15488				
061A-5 078A-5 094A-5 103A-5 144A-5	50 60 75 100	ABB-48431-037 ABB-48431-122 ABB-44500	8 6,44	11552 10892	28Wx10Dx10H 28Wx10Dx10H	ABB-48431-123 ABB-44544	6,39	21955	28Wx16Dx10H			
061A-5 078A-5 094A-5 103A-5 144A-5 166A-5	50 60 75 100 125	ABB-48431-037 ABB-48431-122 ABB-44500 ABB-48431-185	8 6,44 4,3	11552 10892 17067	28Wx10Dx10H 28Wx10Dx10H 28Wx13Dx10H	ABB-48431-123 ABB-44544 ABB-48431-187	6,39 4,3	21955 27520	30Wx18Dx24H			
050A-5 061A-5 078A-5 094A-5 103A-5 144A-5 166A-5 202A-5	50 60 75 100	ABB-48431-037 ABB-48431-122 ABB-44500	8 6,44	11552 10892	28Wx10Dx10H 28Wx10Dx10H	ABB-48431-123 ABB-44544	6,39	21955	28Wx16Dx10H 28Wx16Dx10H 30Wx18Dx24H 30Wx18Dx24H 30Wx18Dx24H			

¹ When using "Low Noise Mode" (parameter 40.01) for high output frequency, see recommendations in the hardware manual

ACS850 drives

		DutyCycle=3sec on	/27sec o	ff		DutyCycle=10sec o	n/50sec	off	
Drive P/N	HP								
ACS850-04-	ND	Resistor Part No.	Ohms	Watts	Dimensions	Resistor Part No.	Ohms	Watts	Dimensions
290A-5	200	ABB-48431-273	2,9	23490	28Wx16Dx10H	ABB-48431-275	2,9	41760	30Wx18Dx32H
	300	ABB-48431-334	2,2	40095	30Wx18Dx32H	ABB-43503	2,27	68450	30Wx18Dx48H
430A-5	350	ABB-48431-334	2,2	40095	30Wx18Dx32H	ABB-43503	2,27	68450	30Wx18Dx48H
	400	ABB-44508	1,72	43916	30Wx18Dx32H	ABB-43504	1,72	82280	30Wx18Dx40H
521A-5	450	ABB-48431-396	1,7	58183	30Wx18Dx32H	ABB-43504	1,72	82280	30Wx18Dx40H
602A-5	500	ABB-48431-455	1,35	68344	30Wx18Dx32H	ABB-44553	1,38	104527	30Wx18Dx72H
693A-5	550	ABB-48431-517	1	67600	30Wx18Dx40H	ABB-48431-519	1	122500	(2) 30Wx18Dx40H
720A-5	600	ABB-48431-518	1	90000	30Wx18Dx48H	ABB-48431-519	1	122500	(2) 30Wx18Dx40H

Three phase 200-240 V applications, stopping duty only

Standard Enclosed Resistor packages ¹

		DutyCycle=3sec on/27sec off				DutyCycle=10sec on/50sec off				
Drive P/N	HP									
ACS850-04-	ND	Resistor Part No.	Ohms	Watts	Dimensions	Resistor Part No.	Ohms	Watts	Dimensions	
06A0-2	1,5	P14494-61	120	300	12Wx5Dx5H	P14494-61	120	300	12Wx5Dx5H	
08A0-2	2	P14494-61	120	300	12Wx5Dx5H	P14494-61	120	300	12Wx5Dx5H	
010A-2	3	ABB-48431-050	80	400	12Wx7Dx5H	ABB-48431-050	80	400	12Wx7Dx5H	
014A-2	3	ABB-41139	44	300	12Wx5Dx5H	ABB-43390	40	800	12Wx7Dx5H	
018A-2	5	ABB-41139	44	300	12Wx5Dx5H	ABB-43390	40	800	12Wx7Dx5H	
025A-2	7,5	P14494-40	21	750	12Wx7Dx5H	P14494-40	21	750	12Wx7Dx5H	
030A-2	10	P14494-40	21	750	12Wx7Dx5H	P14494-41	21	1050	12Wx10Dx5H	
035A-2	10	P14494-40	21	750	12Wx7Dx5H	P14494-41	21	1050	12Wx10Dx5H	
044A-2	15	ABB-41144	13	1200	12Wx10Dx5H	ABB-48431-031	13	1872	12Wx16Dx5H	
050A-2	15	ABB-41144	13	1200	12Wx10Dx5H	ABB-48431-031	13	1872	12Wx16Dx5H	
061A-2	20	ABB-41144	13	1200	12Wx10Dx5H	ABB-48431-031	13	1872	12Wx16Dx5H	
078A-2	25	ABB-48431-031	13	1872	12Wx16Dx5H	ABB-41157	13	2100	19Wx10Dx5H	
094A-2	30	ABB-48431-031	13	1872	12Wx16Dx5H	ABB-44494	13	3333	19Wx10Dx5H	
		DutyCycle=30sec	on/180se	c off	:	DutyCycle=60sec on/180sec off				
Drive P/N	HP									
ACS850-04-	ND	Resistor Part No.	Ohms	Watts	Dimensions	Resistor Part No.	Ohms	Watts	Dimensions	
06A0-2	1,5	P14494-61	120	300	12Wx5Dx5H	ABB-48431-110	120	600	12Wx7Dx5H	
08A0-2	2	P14494-61	120	300	12Wx5Dx5H	ABB-48431-110	120	600	12Wx7Dx5H	
010A-2	3	ABB-48431-050	80	400	12Wx7Dx5H	ABB-48431-052	80	800	12Wx7Dx5H	
014A-2	3	ABB-43390	40	800	12Wx7Dx5H	ABB-44490	41	980	12Wx10Dx5H	
018A-2	5	ABB-43390	40	800	12Wx7Dx5H	ABB-44512	40,6	1303	12Wx13Dx5H	
025A-2	7,5	P14494-41	21	1050	12Wx10Dx5H	P14494-43	21	2000	12Wx16Dx5H	
030A-2	10	P14494-42	21	1500	12Wx13Dx5H	ABB-44515	22	2910	19Wx13Dx5H	
035A-2	10	P14494-42	21	1500	12Wx13Dx5H	ABB-44515	22	2910	19Wx13Dx5H	
044A-2	15	ABB-48431-031	13	1872	12Wx16Dx5H	ABB-44494	13	3333	19Wx10Dx5H	
050A-2	15	ABB-48431-031	13	1872	12Wx16Dx5H	ABB-44494	13	3333	19Wx10Dx5H	
061A-2	20	ABB-44494	13	3333	19Wx10Dx5H	ABB-48431-035	13	4212	26.5Wx10Dx	
078A-2	25	ABB-44494	13	3333	19Wx10Dx5H	ABB-48431-036	13	6292	26.5Wx13Dx5	
							·			
094A-2	30	ABB-48431-035	13	4212	26.5Wx10Dx5H	ABB-48431-036	13	6292	26.5Wx13Dx5	

¹ When using "Low Noise Mode" (parameter 40.01) for high output frequency, see recommendations in the hardware manual

Options Mains circuit

ACS850	_	04	-	XXXX	_	2	+	XXXX
						5		

du/dt filters

du/dt filtering suppresses inverter output voltage spikes and rapid voltage changes that stress motor insulation.

Additionally, du/dt filtering reduces capacitive leakage currents and high frequency emission of the motor cable as well as high frequency losses and bearing currents in the motor.

The need for du/dt filtering depends on the motor age and insulation. For information on the construction of the motor insulation, consult the motor manufacturer. If the motor does not fulfil the requirements of the filter selection table, the lifetime of the motor might decrease. Insulated non-driven end (N-end) bearings and/or common mode filters are also required for motor bearing currents with motors bigger than 100 kW. For more information please see the ACS850 hardware manual.

External du/dt filters

ACS850-04		du/dt filter type (3 filters included in kits marked *)								
		Unprotected (IP00)								
230 V	NOCH0016-60	NOCH0030-60	NOCH0070-620	* NOCH0120-60	* NOCH0260-60	FOCH0260-70	FOCH0320-50	FOCH0610-70		
-03A0-2	-03A0-5		-	-	-	-	-	-	_	
-03A6-2	-03A6-5		-	-	-	-	-	-	-	
-04A8-2	-04A8-5	-	-	-	-	_	-	-	-	
-06A0-2	-06A0-5	-	-	-	-	-	-	-	-	
-08A0-2	-08A0-5		-	-	-	-	-	-	-	
-010A-2	-010A-5	-	-	-	-	-	-	_	-	
-014A-2	-014A-5		-	-	-	-	-	-	-	
-018A-2	-018A-5		-	-	-	-	-	-	-	
-025A-2	-025A-5	_		-	-	-	-	-	-	
-030A-2	-030A-5	_		-	-	-	-	-	-	
-035A-2	-035A-5	_		_	-	-	-	-	-	
-044A-2	-044A-5		-		-	-	-	-	-	
-050A-2	-050A-5	_	-		-	-	_	-	-	
-061A-2	-061A-5	_	-		_	-	-	-	-	
-078A-2	-078A-5	_	-		-	-	-	-	_	
-094A-2	-094A-5	_	-	_		_	_	-	-	
-103A-2	-103A-5	-	-	-		-	-	-	-	
-144A-2	-144A-5	_	-	_		-	-	-	-	
-166A-2	-166A-5	_	-	_		-	_	_		
-202A-2	-202A-5	_	-	_	-		_	_		
-225A-2	-225A-5		-	-	-	_		_	-	
-260A-2	-260A-5		_	_	_	_		_	_	
-290A-2	-290A-5	_	-	_	-	_		_		
-430A-2	-430A-5	-	-	_	-	_		•		
-521A-2	-521A-5		-	-	-	-		-		
-602A-2	-602A-5		-	-	_	_		_		
-693A-2	-693A-5		-	_	-	-		_		
-720A-2	-720A-5	_	-	-	-	-	-	-		

^{■ =} option, external -= not applicable

du/dt filter selection table

Motor type	Nominal mains voltage (U_N)	Motor insulation requirement
ABB M2 and M3 motors	U _N ≤ 500 V	Standard insulation system.
ABB form-wound HXR and AM motors	380 V < U _N ≤ 500 V	Standard insulation system.
ABB random-wound HXR and AM motors	380 V < U _N ≤ 500 V	Check motor insulation system with the motor manufacturer.
Non-ABB random-wound and form-wound	<i>U</i> _N ≤ 420 V	If the insulation system withstands $\hat{U}_{\rm LL}$ = 1600 V and Δt = 0.2 μ s, du/dt filtering is not required. With du/dt filtering the insulation system must withstand $\hat{U}_{\rm LL}$ = 1300 V.
U _N Nominal mains voltage.		
$\hat{U}_{_{\mathrm{LL}}}$ Peak line-to-line voltage at motor to	erminals.	
Δt Rise time, ie, interval during which	line-to-line voltage at motor t	erminals changes from 10% to 90% of full voltage range.

Dimensions and weights of du/dt filters

du/dt filter	Height		Width		Depth	Depth		Weight	
	in	mm	in	mm	in	mm	lb	kg	
NOCH0016-60	7.7	195	5.5	140	4.5	115	5.28	2.4	
NOCH0030-60	8.5	215	6.5	165	5.1	130	10.34	4.7	
NOCH0070-60	10.3	261	7.1	180	5.9	150	20.9	9.5	
NOCH0120-60*	7.9	200	6.1	154	4.2	106	15.4	7	
NOCH0260-60*	15.1	383	7.3	185	4.4	111	26.4	12	
FOCH0260-70	15.0	382	7.5	190	10.0	254	103.4	47	
FOCH0320-50	26.1	662	12.6	319	11.1	282	143	65	
FOCH0610-70	26.1	662	12.6	319	11.1	282	143	65	

^{* 3} filters included, dimensions apply for one filter.

Options PC tools

DriveStudio

User-friendly PC tool for quick drive startup, drive tuning and advanced programming tasks.

Start-up and maintenance tools:

- Fast parameter navigation
- Parameter setting
- Data logging and online drive signal monitoring of multiple signal channels for drive tuning
- Back-up and restore tool for drive parameter and DriveSPC program cloning
- Case sensitive help with detailed descriptions of drive parameters, events and functions
- Overview of the drive performance and status

DriveSPC

DriveSPC is a programming tool that enables easy modification or extension of drive functionality:

- Simple, easy-to-learn function block interface showing drive firmware functions, signals and parameters
- Easy to add user-defined function block programs even on the fast time levels of the drive control
- Function block programming with standard IEC61131 function block library
- Professional programming environment with hierarchy levels, custom circuits, user parameters and copy protection of DriveSPC programs

DriveSize

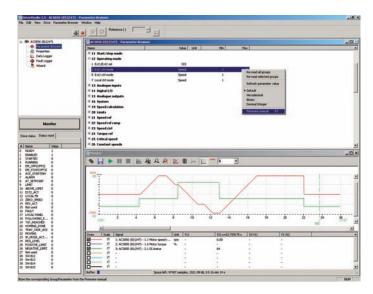
DriveSize is a PC program for helping the user select the optimal motor, frequency converter and transformer, especially in the case where a straightforward selection from a catalog is not possible. Additionally it can be used to compute currents, network harmonics and to create documents about the dimensioning based on actual load.

DriveSize contains the current versions of the ABB motor and AC drive catalogs.

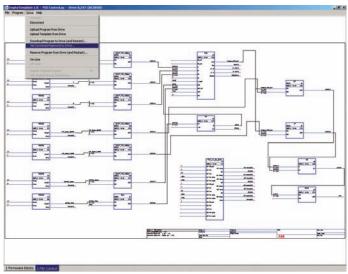
The default values make DriveSize simple to use, and the user is provided with ample options for drive selection. The shortcut keys make drive selection easy while giving the optimal dimensioning result. A manual selection mode is also supported.

DriveSize features:

- Selects the optimal motor, drive unit, supply unit and transformer
- Calculates network harmonics for a single supply unit or for the whole system
- Allows importation of own motor database
- Supplies dimensioning results in graphical and numerical format
- Prints and saves the results







DriveSPC

Options Remote monitoring and diagnostic tools

SREA-01 enables remote access

With drives increasingly being installed in remote locations, it is vital that operational and process data is monitored locally in real time and transmitted to a central location for analysis. Often there is no qualified service personnel stationed at these sites, which makes remote monitoring and diagnosis of the drive and application crucial to process availability.

ABB's SREA-01 Ethernet adapter performs all these remote access tasks. Designed as an optional remote interface module for the drives, the SREA-01 can send process data, data logs and event messages independently, without a PLC or a dedicated on-site computer, and has an internal web server for configuration and drive access.

Connect multiple drives to an Ethernet or GPRS network

In addition to a standard Ethernet port, the SREA-01 has a serial port for connection to a standard GSM/GPRS modem for Internet connectivity in isolated places. The modem connection enables sending e-mail or SMS messages, uploading data files by FTP, or accessing the SREA-01 web pages.

The SREA-01 is connected to the panel port, or alternatively to the Modbus interface, of a drive. A maximum of 10 drives can be connected to a single SREA-01 module over Ethernet or EIA-485 serial communication networks. Simultaneous use of the two connection methods is possible, allowing access to different types of drives. In addition, Modbus TCP commands from a PLC to a drive are supported in the remote monitoring mode.

Collect data logs and integrate drive data in SCADA applications

For collecting data from the drive, process or data analysis, the SREA-01 has a configurable data logger that can store values from the devices to a file, with sample intervals between ten seconds and one hour. The files are stored internally for visualization with a web browser. Data in standard comma separated values (CSV) file format can be imported to applications such as Microsoft Excel for processing.

The collected data logs can be sent by e-mail or FTP, either through a local area network or the Internet. The sending interval can be configured by the user, with logs sent, for example, hourly or weekly. In addition to its data logging functionality, the SREA-01 also has an internal Modbus TCP gateway, providing a standard interface that can be used by supervisory control and data acquisition (SCADA) applications to display drive information in real time.

Receive event messages and alarms, and access the drive remotely

The SREA-01 can be used to monitor the drive and application parameters such as process temperatures, and send alarm messages to maintenance personnel if a set limit is exceeded. Event and alarm messages are sent as SMS messages or by e-mail using the user's own messages. The event conditions and messages can be configured by the user to make them suitable for a number of applications.

At any time, the internal web server of the SREA-01 provides an intuitive user interface for accessing the drives. Travel to sites can often be avoided by using a standard web browser to view and change the drive parameters, monitor the status of all connected devices, and browse the actual faults or history of the installation.



Notes

Notes

Contact us

www.abb.us/drives

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